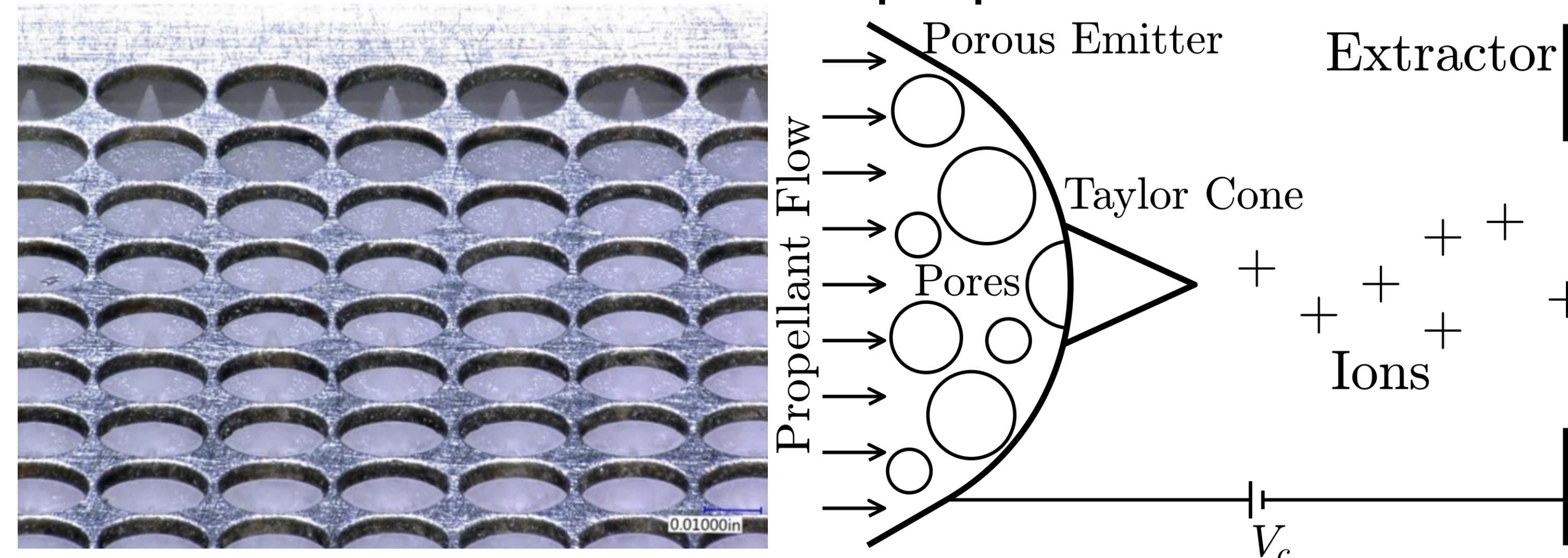


Motivation

Electrospray thrusters are electrohydrodynamic devices that extract charged particles from a conductive liquid to produce thrust in space. In principle, this process is more efficient and scalable than other electric propulsion devices.



But electro sprays are small, requiring arrays of 10^2 - 10^4 individual emitters. At this scale, lifetime and performance can be limited by physical and manufacturing uncertainty. We aim to address this problem with a robust design optimization and testing loop.

We focus here on updating reduced-fidelity models given new data.



Objectives

Reduced-fidelity modeling engenders physical uncertainty by simplifying physics.

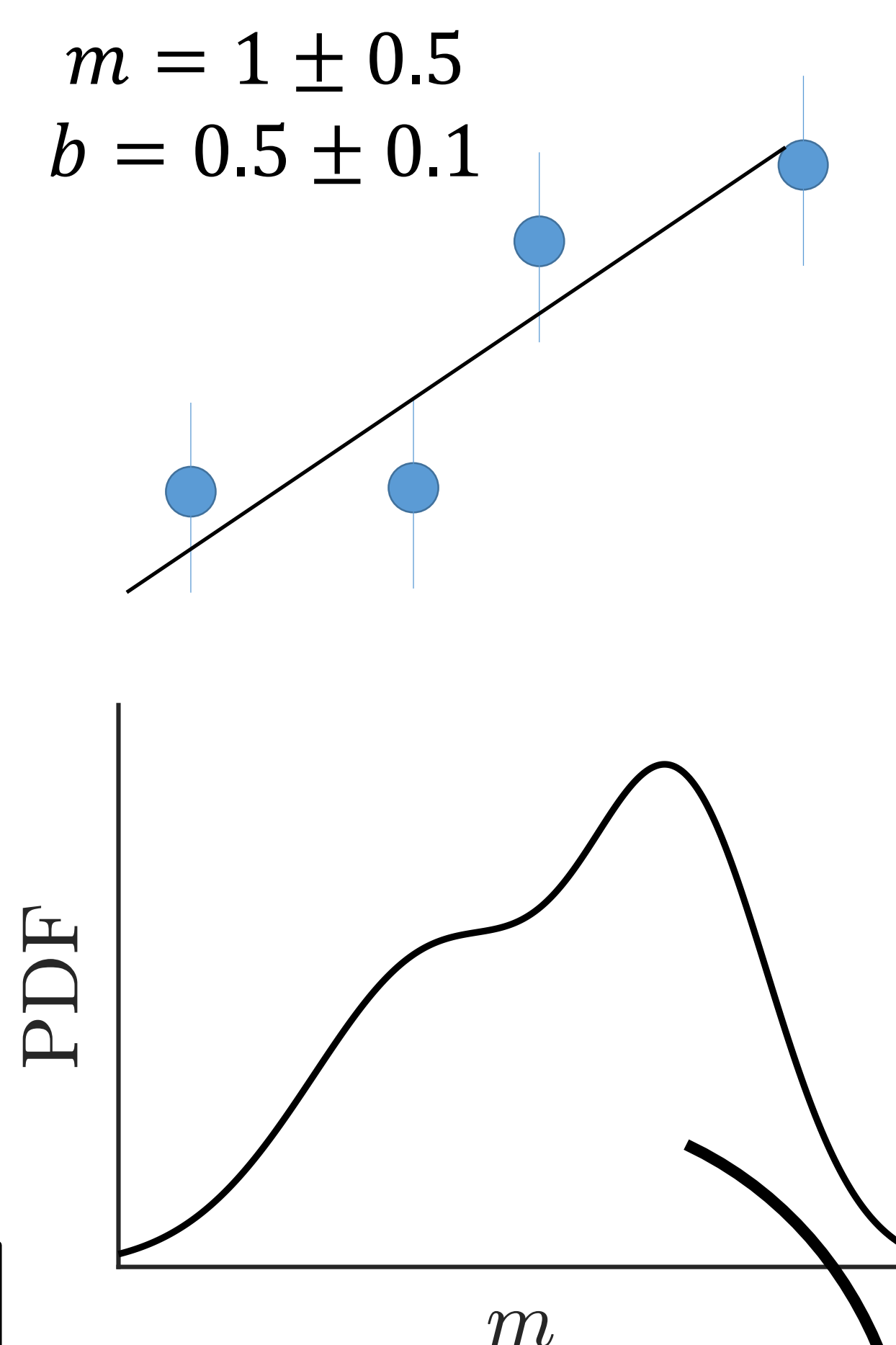
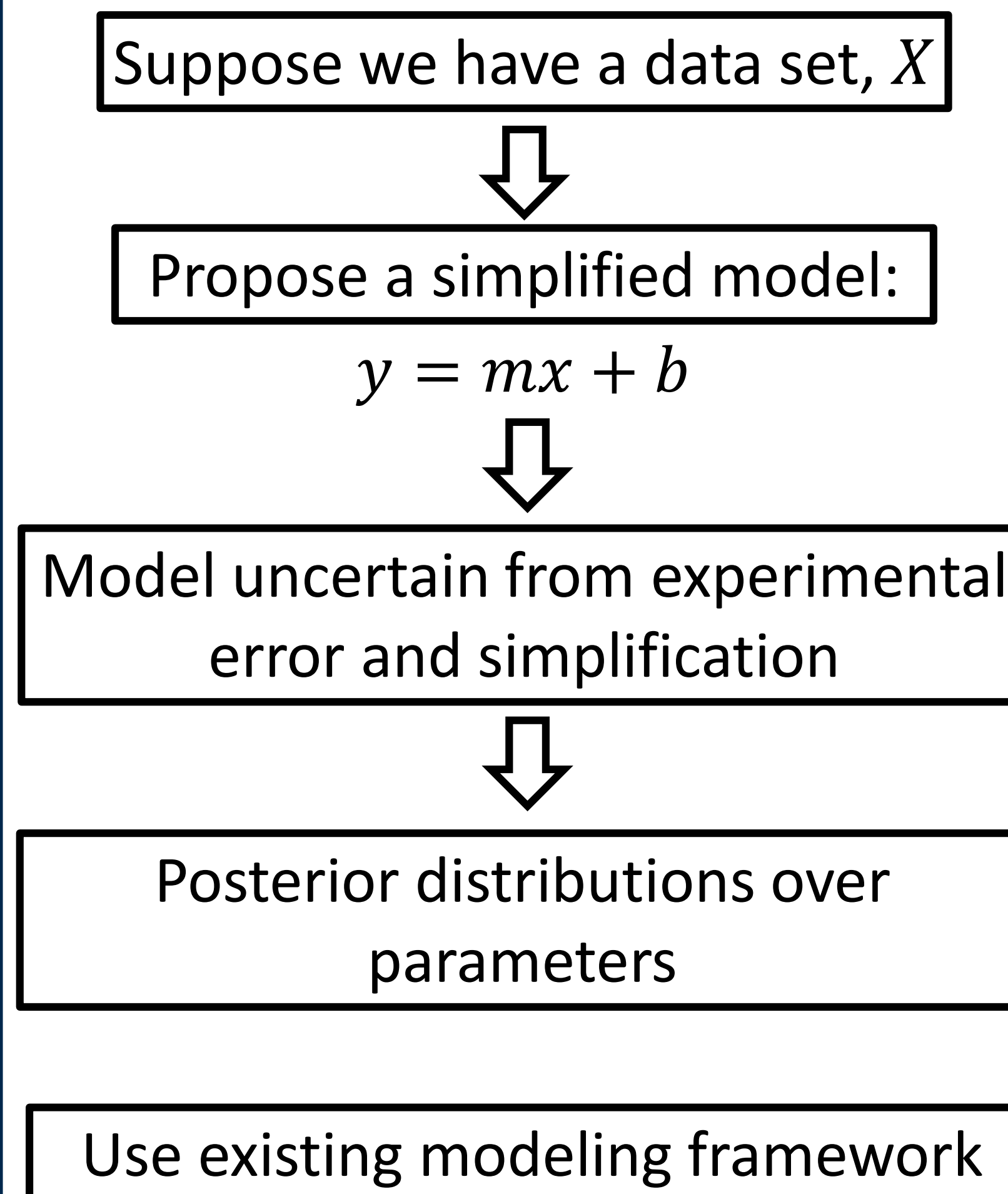
1. How do we rigorously account for this uncertainty?
2. Can we use data to update our state of knowledge?
3. How can we use our knowledge to credibly predict device performance?

Methodology

Bayes' Theorem:

$$\text{prob}(\theta|X, I) = \frac{\text{prob}(X|\theta, I) \times \text{prob}(\theta|I)}{\text{prob}(X|I)}$$

θ : model parameters
 X : data
 I : background knowledge



ESPET
ElectroSpray Propulsion Engineering Toolkit

Sample Many Times to Make Predictions

m, b m, b
 m, b m, b m, b
 m, b m, b

Models

$$I_{ion} = I_{ion,0} + \zeta \frac{V - V_0}{C_R}$$

$$I_{jet} = \alpha I_{jet,0} \left(\frac{Q}{Q_0} \right)^{1/2}$$

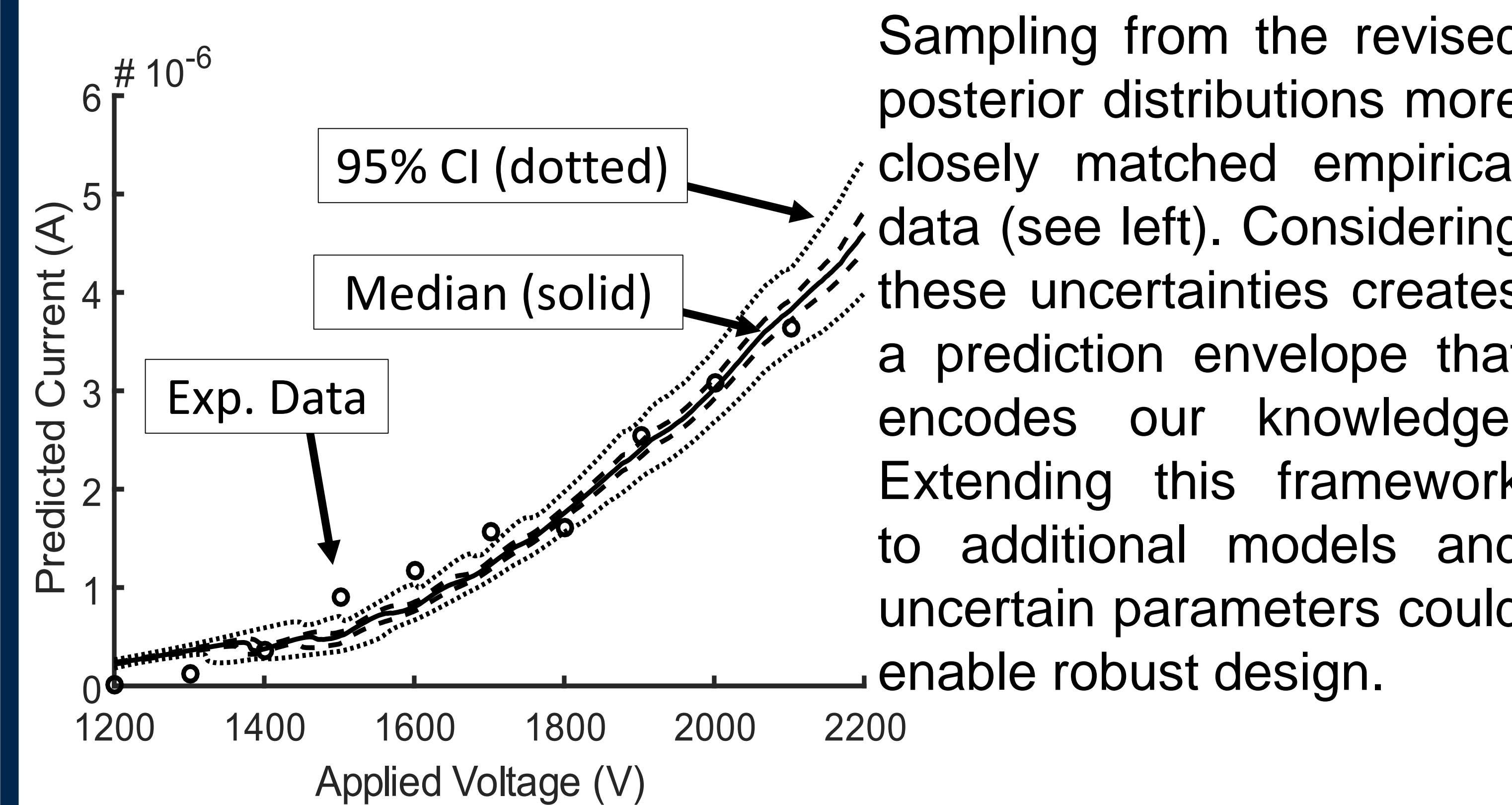
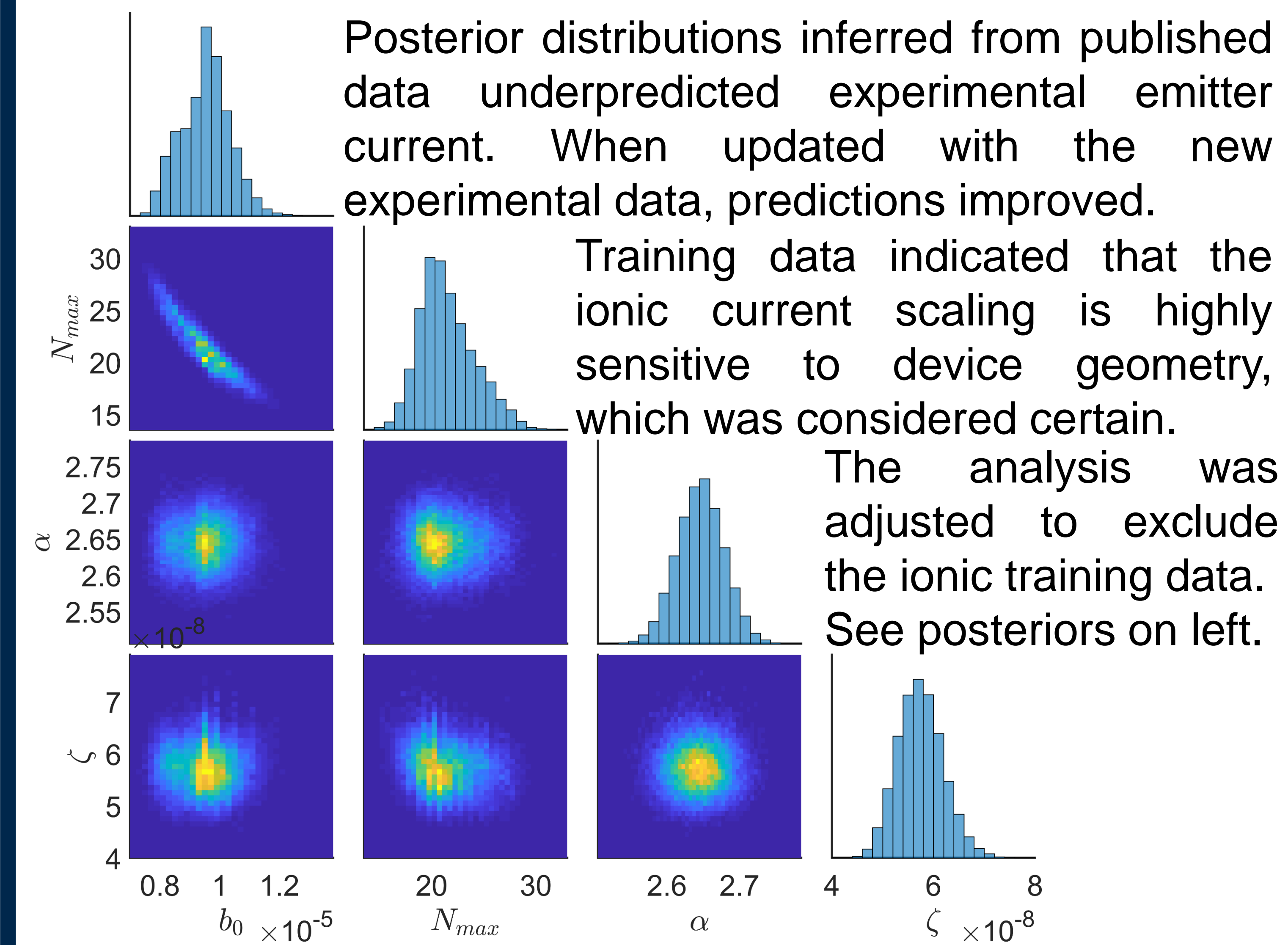
$$i = (N_{max} - 1) \left(1 - \frac{(r_{base} - r_0)}{b_0} \right)^4 + 1$$

$$r_{base} = \frac{4\gamma a^2 \text{atanh}^2(\eta_0) (1 - \eta_0^2)^2}{\epsilon_0 V^2}$$

Model Inputs:
 V : emitter voltage
 I : current (ionic or jet)
 Q : vol. flow rate
 r_0 : pore radius
 γ : surface tension
 C_R : scale hyd. Imped.
 V_0 : onset voltage
 I_0 : onset/scale current
 Q_0 : scale vol. flow rate
 a, η_0 : emitter geometry

Inferred Parameters:
 $\zeta, \alpha, b_0, N_{max}$

Results



Conclusions

1. Bayesian inference can be used to describe the physical uncertainty of reduced-fidelity models.
2. Performance is highly sensitive to uncertain device geometry, motivating a probabilistic problem.
3. Additional model development may be necessary to capture other phenomena.

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